An optimal reactive power control method for distribution network with soft normally-open points and controlled air-conditioning loads

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1. Introduction

Load demands of distribution systems usually maintains at a high level in the summer and the winter, because of seasonal temperatures in a longtime. Because of the heavy load condition of distribution networks, the low-voltage problems are widely occurring and influencing the power supplying quality of consumers [1]. For urban areas, the maximum air-conditioning loads can reach 30–40% of the peak load in a day [2,3]. For example, it is estimated that air-conditioning loads are in a proportion of 43% in 2016 and shows an increasing trend in recent years in Chengdu, China. Thus, the demand-side management (DSM) of aggregate air-conditioning loads is introduced to encourage clients to decrease the power usage during peak load periods by Electric Power Research Institute (EPRI) [4]. There are many methods to engage clients in DSM, including pricing-based approaches (time-of-use pricing, critical-peak pricing, peak-time rebate, and real-time pricing) as well as direct load control (DLC) [5–8]. The DLC programs are mostly applied when the system is in an extreme event (such as high production costs, low system reliability) to provide the ability of power balance and frequency regulation by shedding partial loads. And the air-conditioning loads have a large amount of capacity for heat storage, which have potentials for power load regulations by direct load control (DLC) conducted by electric power companies [8]. To alleviate the low-voltage problems in the distribution network in the heavy load conditions, the DLC of thermostatically controlled air-conditioning loads is an effective measure for shifting and averting the peak load [9–11] when a reasonable cycle control is implemented for the air-conditioning loads in the power scheduling procedure.

Active control of power flows and voltages by power electronic devices is an alternative measure to address the low-voltage problems of distribution networks [12,13]. Soft normally-open points (SNOP) are power electronic devices replacing normally-open switches connecting the adjacent feeders. The concept of SNOP is proposed in [14] to enhance the flexibility of current distribution networks by little equipment or infrastructure upgrades. There are three types of topologies can be adopted for the SNOP, including back-to-back voltage source converter (VSC), unified power flow controller, and static series synchronous compensator [15–18]. The control modes of SNOP employed back-to-back VSC are analyzed during the normal operation condition and the fault isolation and supply restoration under grid fault condition.
SNOP, the starting voltage constraint of air conditioners can be enforced to isolate the voltage disturbance on one feeder from the other feeder of air conditioners in starting procedure may cause voltage collapse of
started up or shut down back and forth, when the room temperature
feeders with the heavy air-conditioning loads.

During the cycle control of DLC, the air-conditioning loads have to be started up or shut down back and forth, when the room temperature goes up and down. In particular, the high reactive power consumption of air conditioners in starting procedure may cause voltage collapse of the network. If the voltage does not satisfy the starting requirement, these air-conditioning loads cannot be started up in this cycle [22,23]. By the active power regulation and reactive power compensation of SNOP, the starting voltage constraint of air conditioners can be effectively relieved in the cycle control. The introduction of SNOP can guarantee the security of the cycle control of air-conditioning loads in distribution networks, and also can improve the load balancing level between different distribution feeders. In [9,10], the cycle control of air-conditioning loads is adopted to mitigate the unbalance between power supply and demand in the presence of renewable power generation, and the distributed model predictive control scheme is proposed to control the aggregate air-conditioning loads for the ancillary load balancing service in [24]. TheRefs. [16,25–27] indicate that the DLC of aggregate loads and the power control of SNOP are both the distributed flexible resources in smart distribution networks, while the existing studies do not develop the utilization potential of SNOP to support the voltage control of distribution network with the DLC air-conditioning loads. In addition, the critical starting voltage of air-conditioning loads is a key indicator to assess their starting processes during the cycle control [28]. The critical starting voltage should be incorporated into the DLC of air-conditioning loads to determine whether the air conditioners are successfully started up.

To satisfy the voltage control requirements of distribution network with DLC and SNOP in consideration of the starting processes of air-conditioning loads, this paper proposes an analytical method to calculate the critical starting voltage of aggregate air-conditioning loads according to DLC control mode and the starting voltage characteristic. In the constraints of voltage quality of sensitive loads and starting voltage of air-conditioning loads, an optimal reactive power control method for a distribution system is established by using SNOP and the other voltage adjusting and reactive power compensation devices. The method is a collaborative integrated solution for demand responses and voltage quality enhancements. The proposed technique is verified by simulation results of a practical 53-bus 10 kV distribution system.

2. Critical starting voltage of air conditioning load

For the resource of demand response of air-conditioning loads with heat storage capacity, the DLC cycle control can be applied to provide load balancing service. In Fig. 1(a), the DLC aggregate has n controlled air-conditioning loads \(D_1, D_2, ..., D_n\), and the aggregate is in charge of the loads in a same feeder. According to the dispatching commands of an electric power company, the aggregate determine the on/off status of air conditioner in the DLC cycle control for load shedding [11].

Fig. 1(b) shows the cycle control of air conditioners when \(n = 10\), which can be numbered from 1 to 10 (corresponding to the 1st to 10th air conditioners) in the small square box. If the room temperature drops to the lower setting \(T_{\text{min}}\), the relevant air conditioner will be off status which is the gray box. When the room temperature rises to \(T_{\text{max}}\), the air conditioner needs to be started up corresponding to the on status of white box.

In a control cycle from 0 to \(t_{\text{on}}\) the on status duration of an air conditioner is \(t_{\text{on}}-t_{\text{off}}\). The starting characteristic of air conditioner can be represented by an induction motor [23,28], in which the starting electromagnetic torque is proportional to the square of the applied voltage. When the supply voltage is connected to the stator of an induction motor, a rotating magnetic field is produced, and the rotor starts rotating. During the starting process, the rotor speed rises from zero to the rated speed due to the driving electromagnetic torque is larger than the braking mechanical torque, and then the induction motor will operate at an equilibrium point that the electromagnetic torque is equal to the mechanical torque [29]. At the starting time of air conditioner, the rotor slip is unity, and the starting current is very large. The corresponding reactive power is closed to 4–6 times the rated power of air-conditioning loads, which will result in a sharp voltage drop at the connected point of air conditioners. The critical starting voltage is the minimum condition of the starting of air conditioners. Once the terminal voltage is lower than the critical starting voltage, there are no equilibrium points between the electromagnetic torque and the mechanical torque. And then the electromagnetic torque is always lower than the mechanical torque, so that the speed of air conditioner cannot be accelerated to the rated speed, and the air-conditioning load will fail to start. When the terminal voltage is larger than the critical starting voltage, the motor speed can be accelerated for the successful startup of air-conditioning load. Thus the DLC cycle control of air-conditioning loads will keep working when the terminal voltage satisfies the minimum condition of the starting of air conditioners; otherwise the DLC will fail. The critical starting voltage has to be determined to judge whether the system voltage meeting the starting conditions of air-conditioning loads.

The power demand during the starting of air conditioner is mainly from a compressor which has the similar dynamic voltage characteristic with induction motor. Fig. 2 shows the electromagnetic and mechanical torques-speed curves of an air-conditioning load where the parameters are in [28]. When the starting voltage is high enough, there are intersection points (stable equilibrium points) between the curves of electromagnetic torque \(T_e\) and mechanical torque \(T_m\). In this case, the motor speed \(\omega_m\) can be accelerated to the equilibrium point after the starting process [29]. If the terminal voltage is lower than the critical starting voltage, there are no intersection points between the curves of \(T_e\) and \(T_m\). The mechanical torque is still higher than the electromagnetic torque under different speeds, so the motor cannot run stably on the normal equilibrium state.

The mechanical torque \(T_{air}\) of air-conditioning load is proportional to the square of the rotor speed \(\omega_{air}\) [23], and the electromagnetic torque \(T_e\) is in terms of the rotor speed \(\omega_r\) and the terminal voltage \(U\) in Fig. 2. The critical starting voltage \(U_{cr}\) can be got by \(T_e(\omega_{\text{max}} U_{cr}) = T_{air}(\omega_{\text{max}})\), where \(\omega_{\text{max}}\) is the rotor speed corresponding to the maximum electromagnetic torque. For the case in consideration of the network impedance, \(U_{cr} = 0.95\) pu. However, there are still stable equilibrium points between \(T_e\) and \(T_{air}\) when \(U = 0.95\) pu in the case without the network impedance that meets the starting requirement of air conditioner. Thus, it is needed to consider the network impedance to determine the critical starting voltage.

Using the equivalent circuit of induction motor as an air-conditioning load, the equivalent circuit of an aggregator with \(n\) controlled air-conditioning loads is shown in Fig. 3. \(U_i\) is the voltage at the connecting point of aggregator; \(R_0\) and \(X_0\) (\(k = 1, 2, ..., n\)) are the line resistance and reactance; \(R_{air}, R_{s}, X_{s}\) and \(X_{r}\) are stator-side and rotor-side resistance and reactance of \(k\textsuperscript{th}\) air-conditioning load; \(X_{air}\) is the
magnetizing reactance; \( s_k = (\omega_s - \omega_{sk})/\omega_s \) is the rotor slip where \( \omega_s \) is the mains angular frequency, \( \omega_{sk} \) is the rotor angular speed. To achieve the Thevenin voltage and impedance from the connecting point of \( k \)th load to the network, it is assumed that the \( k \)th air-conditioning load is not connected (the node \( k \) is open circuit). And then the impedance matrix \( Z \) of the residual network can be got by the impedance parameters and the known rotor slips of the other air-conditioning loads. The diagonal element \( Z_{kk} \) of \( Z \) is the Thevenin equivalent impedance of node \( k \) [30]. Since the voltage source \( U_i \) is the only source in Fig. 3, the Thevenin voltage at the node \( k \) is,

\[
U_{ck} = \frac{Z_{kk} U_i}{\sqrt{1 + X_k^2}}
\]  

(1)

where \( Z_{kk} \) is the element of the impedance matrix \( Z \), and the \( Z \) is formed by the line impedances, the impedances and rotor slips of air-conditioning loads except the \( k \)th air-conditioning load. The rotor speeds of maximum \( T_e \) are same under different terminal voltages (Fig. 2) since \( T_e \) is proportional to the square of terminal voltage.

The rotor current equations of the network when \( U_i = 1 \text{ pu} \) can be obtained, which corresponds to \( T_{ek} - T_{mk} = 0 (k = 1, 2, \ldots, n) \) of \( n \) loads. The equations are solved by Newton-Raphson method to obtain rotor currents and rotor slips of air-conditioning loads at equilibrium points [29]. Substituting the rotor slips into \( Z \), the Thevenin voltage and impedance at node \( k \) can be obtained. Fig. 4(a) shows the Thevenin equivalent circuit of \( k \)th air-conditioning load, and Fig. 4(b) is the simplified equivalent circuit of Fig. 4(a). The equivalent voltage and impedance are modified as,

![Figure 1. Cycle control of air-conditioning loads: (a) network structure of a load aggregator and (b) cycle control modes.](image)

![Figure 2. Electromagnetic and mechanical torques of an air-conditioning load.](image)

![Figure 3. Equivalent circuit of an aggregator with air-conditioning loads.](image)
of distribution system with SNOP and DLC. Their load-cutting capacities.

Before a day, each participating load aggregator is determined. One day before the starting time of DLC cycle control process, the voltage magnitudes of controlled air conditioners should be greater than or equal to the critical starting voltage at the connecting point of an aggregator has to meet the starting condition of all loads. The critical starting voltage \( U_{cr} \) of an aggregator is the minimum voltage meeting the torque balance of air-conditioning loads.

The mechanical torque of air-conditioning load includes the variable part linearly changing with the square of speed and the constant part depending on the friction loss. The mechanical torque of \( k \)th air-conditioning load is,

\[
T_{mk} (\omega_{mk}, U_l) = T_{mk} (\omega_{max}^2) + T_{mk} (\omega_{min}^2)
\]

where \( T_{mk} \) and \( \omega_{mk}^2 \) are the coefficients of constant and variable parts of mechanical torque. The critical starting voltage of \( k \)th air-conditioning load can be calculated by \( T_{mk} (\omega_{max}, U_l) = T_{mk} (\omega_{max}) \). When there is no controlled air-conditioning loads started up at the same time, the voltage at the connecting point of an aggregator has to meet the starting conditions of all \( n \) loads. The critical starting voltage \( U_{cr} \) of an aggregator is the minimum voltage meeting the torque balance of air-conditioning loads.

\[
U_{cr} = \{\min (U_l) | T_{mk} (\omega_{max}, U_l) \geq T_{mk} (\omega_{max}), k \in [1, n]\}
\]

It is concluded from the above mentioned, the optimal load-cutting assignment of controlled air conditioners: Different controlled air conditioners are widely connected into different distribution transformer areas. Taking into account, if it is unreasonable for load reduction between controlled air conditioners in different distribution transformers, this feeder may appear reactive power imbalanced problem, which can deteriorate reactive power flowing in a long-distance transmission. Or even worse, it will lead a problem of insufficient starting voltage magnitude of DLC air conditioners. Thus the low-voltage problem is still unable to be solved effectively.

2) The starting voltage requirement of controlled air conditioners: An adequate supply voltage is essential for starting air conditioners. If they have insufficient voltage, those rooms in which air conditioners shut down, will increase room temperatures rapidly. Bad room temperatures have bad influence on consumers directly, which may have load aggregators paid off. To avoid this situation, the voltage magnitudes of controlled air conditioners should be greater than or equal to the critical starting voltage at the connecting point of load aggregators.

3) The deviation between practical and planned active power reduction of air-conditioning loads: Controlled air conditioners play a great role in room temperatures. Due to different room temperatures, it will appear many on/off combinations, which may lead to have a load-cutting deviation problem between practical active power reduction and planned active power reduction. To minimize this deviation as much as possible, the SNOP can be used to regulate the active power transferred between different feeders. Zero deviation between actual reduction and planned reduction by transferring deviation loads to other feeders is available.

It is concluded from the above mentioned, the optimal load-cutting assignments for controlled air-conditioning loads, the optimal control of voltage-adjusting devices and transfer and compensation powers of SNOP are integrated into the proposed model. It is assumed that \( N \) different controlled air-conditioning loads at the low-voltage side of different distribution transformers are connected into a feeder; \( \Omega_{SNOP} \) SNOPs connect the feeder to the other feeders. The load reductions of air-conditioning loads are defined as \( \Delta P_{D1}, \Delta P_{D2}, \ldots, \Delta P_{Dn} \) respectively, as shown in Fig. 5. For the electric power dispatch center, the total amount of planned air-conditioning load reduction is assumed as \( \Delta P_f \).

Due to the short lines between distribution transformers and air-conditioning loads, the voltage losses on those lines are negligible. The optimization variables of the proposed model are on/off status of \( N \) controlled air-conditioning loads and their corresponding load reductions, the active power and reactive power of all SNOP, the reactive power compensation at the low-voltage side of distribution transformers, the reactive power compensation at 110 kV substation and its main transformer ratios. In DLC cycle control process of air-conditioning loads, the low-voltage problem of distribution system can be solved through the effective load reduction and optimal reactive power flow control. Therefore, the three objectives of optimal reactive power flow control are proposed in the proposed model.

1) The sufficient load-cutting of air-conditioning loads eliminate the low-voltage problem in distribution systems. The semi-absolute

\[
U_{lk} = \frac{jX_{lk} U_{lk}}{R_{lk} + j(X_{lk} + X_{mk})} + Z_{lk}
\]

\[
R_{lk} + jX_{lk} = \frac{jX_{lk}(R_{lk} + jX_{lk} + Z_{lk})}{R_{lk} + j(X_{lk} + X_{mk}) + Z_{lk}}
\]

From the simplified equivalent circuit in Fig. 4(b), the electromagnetic torque of \( k \)th air-conditioning load is,

\[
T_{mk} (\omega_{mk}, U_l) = \frac{U_{mk}^2}{s_k (R_{lk} + R_{mk}/s_k)^2 + (X_{lk} + X_{mk})^2}
\]

where \( s_k \) and \( U_{lk} \) are in terms of \( s_{0lk} \) and \( U_l \) respectively. By the first derivative of (4) equal to 0, the rotor speed \( \omega_{max} \) corresponding to the maximum electromagnetic torque is calculated as,

\[
\omega_{max}^2 = \frac{R_{lk} \omega_k}{\sqrt{R_{lk}^2 + (X_{lk} + X_{mk})^2}}.
\]

The mechanical torque of air-conditioning load includes the variable part linearly changing with the square of speed and the constant part depending on the friction loss. The mechanical torque of \( k \)th air-conditioning load is,

\[
T_{mk} (\omega_{mk}^2, U_l) = T_{mk} (\omega_{max}^2) + T_{mk} (\omega_{min}^2)
\]

where \( T_{mk} \) and \( \omega_{mk}^2 \) are the coefficients of constant and variable parts of mechanical torque. The critical starting voltage of \( k \)th air-conditioning load can be calculated by \( T_{mk} (\omega_{max}, U_l) = T_{mk} (\omega_{max}) \). When there is no controlled air-conditioning loads started up at the same time, the voltage at the connecting point of an aggregator has to meet the starting conditions of all \( n \) loads. The critical starting voltage \( U_{cr} \) of an aggregator is the minimum voltage meeting the torque balance of air-conditioning loads.

\[
U_{cr} = \{\min (U_l) | T_{mk} (\omega_{max}, U_l) \geq T_{mk} (\omega_{max}), k \in [1, n]\}.
\]
The on/off status \( \mu_j \) of a controlled air-conditioning load \( j \) is determined by both room temperatures and the limit temperatures of cycle control.

\[
\mu_j = \begin{cases} 
1, & T_{j,\min} \leq T_j \leq T_{j,\max} \\
0, & T_j > T_{j,\max} 
\end{cases} 
\tag{9}
\]

where \( \mu_j \) represents the controlled state of the controlled air-conditioning load \( j \), which \( \mu_j = 1 \) indicates that the air-conditioning load \( j \) is shut down; on the contrary, \( \mu_j = 0 \) indicates that the air-conditioning load \( j \) is switched on. \( T_j \) represents the room temperature of the air-conditioning load \( j \). \( T_{j,\min} \) and \( T_{j,\max} \) are the minimum and maximum critical temperatures for the air-conditioning load \( j \) in the DLC cycle control, respectively.

A number of controlled air conditioners are switched on, when room temperatures are higher than \( T_{j,\max} \). This causes a large load increase in distribution systems, and perhaps leads to the low-voltage problem again. In order to avoid the low-voltage problem once again, there will be extending time periods of air conditioners that are turned off, even though the room temperature of controlled air-conditioning load \( j \) is higher than \( T_{j,\max} \). This is

\[
\mu_j = 1, \quad T_j \geq T_{j,\max}. 
\tag{10}
\]

However, room temperatures are continuing to be raised and extended, if air conditioners are turned off, which causes bad influence on the comfort of users. Thus, the objective function of minimizing deviation between the controlled state and the ideal state of controlled air-conditioning load \( j \) is used to eliminate the negative effect on the comfort of users.

\[
\min \ f_2 = \sum_{j=1}^{N} (\mu_j^* - \mu_j)^2 
\tag{11}
\]

where \( \mu_j^* \) represents the ideal control state of controlled air-conditioning load \( j \) satisfying (9); \( \mu_j \) represents the practical control state of controlled air conditioners.

3) To maximum the economic benefits of distribution system, the active power losses of the distribution network and the SNOP should be as small as possible.

\[
\min \ f_3 = P_{\text{loss,NET}} + \sum_{l=1}^{\alpha_{\text{SNOP}}} P_{l,\text{SNOP}}^l
\tag{12}
\]

where \( P_{\text{loss,NET}} \) is the active power loss of the network; \( P_{l,\text{SNOP}}^l \) is the active power loss of \( l \)-th SNOP, which is made up of the losses of semiconductors, passive components and the cooling system. The \( P_{l,\text{SNOP}}^l \) is divided into three components: no load loss, linear and quadratic loss depending on the converter current [17], so that it can be measured in terms of the apparent power of the converter. The \( P_{l,\text{SNOP}}^l \) can be obtained as,

\[
P_{l,\text{SNOP}}^l = a_{l,\text{SNOP}}^l + b_{l,\text{SNOP}}^l S_{l,\text{SNOP}}^l + P_{l,\text{SNOP}}^l,
\tag{13}
\]

where \( S_{\text{SNOP}}^l \) represents the apparent power of \( l \)-th SNOP; \( a \) and \( b \) are the coefficients of the active power loss; \( P_{l,\text{SNOP}}^l \) represents the fixed loss of \( l \)-th SNOP. It is noted that a SNOP contains two VSCs sharing a DC link, so that the active power loss of a SNOP is the sum of the power losses of these two VSCs, and the power loss of each VSC can be calculated by (13). In the above three objective functions, we consider the low-voltage problem-solving objective is as the priority, which is for keeping security operation of distribution systems; and then minimizing negative impacts on the comfort of users as much as possible in the DLC cycle control, and ensuring demand response working effectively in the long-term; at last, the economic benefits of distribution system is finally considered.

3.2. Constraints of optimal reactive control model

The constraints of the model include the network power flow constraints, the operation constraints of conventional reactive power compensation and main transformer ratio, and the operation constraints of controlled air-conditioning loads and SNOPs. The operation constraints of controlled air-conditioning loads should take the critical starting voltage into consideration, which is the voltage magnitude \( U_{D,j} \) greater than or equal to the critical starting voltage \( U_{c,j} \) at the connecting point of aggregators. The operation constraints for air-conditioning loads are,

\[
\begin{align*}
\Delta P_{D,j} &\leq \mu_j \Delta P_{D,j} \leq \Delta P_{Dj}^c \\
\Delta Q_{D,j} &\leq \mu_j \Delta Q_{D,j} \leq \Delta Q_{Dj}^c \\
U_{c,j} &\leq U_{D,j} \\
\mu_j &\in [0, 1]
\end{align*}
\tag{14}
\]

where \( U_{c,j} \) represents the critical starting voltage of the controlled air-conditioning load \( j \) obtained by (7); \( \tan y \) is the power factor of air-conditioning load, \( \Delta P_{D,j} \) and \( \Delta Q_{D,j} \) are the minimum and maximum reduction of controlled air-conditioning load \( j \).

Fig. 6 shows that two distribution feeders are connected through a SNOP composed of VSCI and VSCL sharing a DC link. The SNOP can accurately control the transfer active power through two feeders, while
provide reactive power compensation supporting for those two feeders as well. For \( l \)th SNOP in Fig. 6, \( P_{l,SNOP}^i \) and \( Q_{l,SNOP}^i \) are the active and reactive powers of VSC\(_i\) injecting into feeder 1, and \( P_{l,SNOP}^j \) and \( Q_{l,SNOP}^j \) are the active and reactive powers of VSC\(_j\) injecting into feeder 2. The reactive power adjustments of VSCs are independent, while their active powers need to meet the conservation of energy. That is the sum of active powers of VSCs and the active power loss of SNOP is equal to zero. To consider the power loss of the SNOP, the active power transfer constraint of \( l \)th SNOP is,

\[
P_{l,SNOP}^i + P_{l,SNOP}^j + P_{Loss,SNOP}^l = 0 \quad l \in \Omega_{SNOP}
\]

where \( \Omega_{SNOP} \) is the SNOP set; \( P_{Loss,SNOP}^l \) is the power loss of \( l \)th SNOP, which is the sum of the power losses of VSC\(_i\) and VSC\(_j\), and \( P_{l,SNOP}^i \) and \( P_{l,SNOP}^j \) can be calculated by (13). The reactive power injected constraints is,

\[
\begin{align*}
Q_{l,SNOP}^{i,\min} & \leq Q_{l,SNOP}^i \leq Q_{l,SNOP}^{i,\max} & l \in \Omega_{SNOP} \\
Q_{l,SNOP}^{j,\min} & \leq Q_{l,SNOP}^j \leq Q_{l,SNOP}^{j,\max} & l \in \Omega_{SNOP}
\end{align*}
\]

(16)

where \( Q_{l,SNOP}^{i,\min}, Q_{l,SNOP}^{i,\max}, Q_{l,SNOP}^{j,\min}, Q_{l,SNOP}^{j,\max} \) are the lower and upper limits of the reactive power of two VSCs in \( l \)th SNOP. And the apparent power of VSCs cannot exceed the rated capacity. The SNOP capacity constraint is,

\[
\begin{align*}
\sqrt{P_{l,SNOP}^i + Q_{l,SNOP}^i} & \leq S_{l,SNOP}^i & l \in \Omega_{SNOP} \\
\sqrt{P_{l,SNOP}^j + Q_{l,SNOP}^j} & \leq S_{l,SNOP}^j & l \in \Omega_{SNOP}
\end{align*}
\]

(17)

where \( S_{l,SNOP}^i \) and \( S_{l,SNOP}^j \) are the rated capacities of two VSCs in \( l \)th SNOP. The active power transfer and reactive power compensation of SNOP are applied to support the voltage control of the network with air-conditioning loads.

Since SNOPs regulate the transfer active power between two feeders, the practical load reduction can be equal to the planned load reduction. Thus, the operation constraints of SNOP are composed of (8) (10), and the active power balance constraint as follows:

\[
\sum_{j=1}^{N} \mu_j \Delta P_{l,j} = \Delta P_T + P_{l,SNOP}^k = 0 \quad k \in \Omega_{SNOP}
\]

(18)

The constraints of the proposed model contain the nonlinear power flow equations and the 0–1 on/off status of controlled air conditioners. This model is a mixed nonlinear integer with multi-objective programming problem. Since the model optimization variable is 0–1 integer variables and continuous variables, we can take 0–1 integer variables as a population, and continuous variables as a population. A parallel cooperative co-evolutionary differential evolution algorithm [32] is used to solve the model due to the better solution efficiency.

4. Case study

A practical 10 kV distribution system contains 54 buses shown in Fig. 7. A 110 kV substation has been installed reactive power...
compensation capacitors buses of 2, 5, 13, 15, 19, 26, 46, 49 and 54. The basic power is 100 kVA and basic voltage is 10 kV. Bus 1 is the swing bus of system. There are SNOP1, SNOP2 and SNOP3 with capacities of 1000, 800 and 1500 kVA respectively, 7 air-conditioning loads connected to bus 4, 12, 14, 18, 25, 45 and 53 managed by the load aggregator. The three SNOPs connect the 54-bus distribution system to the feeders A, B and C respectively, and the networks of feeders A, B and C are shown in Fig. 8. The coefficients \( a \) and \( b \) of the active power loss of SNOP1, SNOP2 and SNOP3 are 0.02 and 0.01, 0.016 and 0.08, 0.03 and 0.02, respectively. It is assumed the room temperatures are within \([26 \, ^\circ C, 28 \, ^\circ C]\). The critical starting voltages of load aggregator are about 226 V, which is 0.97pu. The parameters of air-conditioning loads are seen in Table 1, and the time-varying temperature equation is used to calculate the temperature [9]. The load data and room temperatures are from SCADA and remote sensors of air conditioners in Chengdu, China. The data are from 12:00 am to 13:00 pm with 5 min as intervals on 21th, July 2016. The scheduled load-cutting time between the dispatching center and the load aggregator is 12: 00–13: 00 with an amount of 224 kW load-cutting. The voltage allowable range is from 0.9 pu to 1.07 pu.

4.1. Comparison of low-voltage control effects

Fig. 9 shows the voltages for 54-bus power distribution system obtaining by the power flow at the initial status of air-conditioning loads and the initial room temperatures of Table 1. In Fig. 9, the ideal voltages after DLC control of [9] indicate that the voltage magnitudes with ideal DLC load-cutting, in this extreme case that all air-conditioning loads are cut off, and the air-conditioning load reduction reaches the maximum amount. And the DLC control of [9] cannot determine whether the cutting air-conditioning loads can be started up in the next control cycle. The lower boundary of voltage security is the composed by the critical starting voltage magnitudes constraints and the voltage security constraints. The critical starting voltage magnitudes constraints are determined by practical states in the 1st time-period shown in Table 2. And additionally, Table 2 gives ideal control status of all controlled air conditioners.

The room temperatures of air conditioners in bus 4, bus 12 and bus 14 we given from Table 1 are below 29°, thus DLC cycle control turns these air conditioners off. For air conditioners in bus 25, although it is above 28°, that they are switched off as well in DLC cycle control. In order to have controlled air conditioners that are switched off to get started, sufficient voltage magnitudes of those 4 buses are greater than or equal to the critical starting voltage magnitude 0.97 p.u. It is assume that if all of controlled air conditioners are switched off after DLC cycle control, total system loads are the minimum and ideal voltage magnitudes are seen as the curve after DLC control of [9] in Fig. 9. The feasible voltages of the proposed control method are between the curve...
after DLC control and the curve before the reactive power control.

In Fig. 9, the voltages of bus 34–46, 48, 52 and 53 are below the voltage security constraints. There are existing serious low-voltage problems in bus 40–bus 46, bus 48, bus 53 which are load buses of distribution transformer. But, they are not appearing any low-voltage problems after the proposed control methods, and critical starting voltage magnitudes constraints at bus 4, 12, 14 and 25 are satisfied as well. Comparing the voltages by the proposed control methods with and without SNOP, the voltage magnitudes at bus 12 and bus 14 are above critical starting voltage magnitude about 0.015–0.02 when the SNOPs are not connected into distribution system after DLC cycle control. It also has a possibility of DLC control failures if the consuming loads are further increasing in a rapid speed. But for 10 kV distribution system with SNOP, all voltage magnitudes at each bus are higher than voltage magnitudes in distribution system without SNOP. It can be seen that the DLC control can continue to working, even though consuming loads are further increasing in a rapid speed. It is greatly effective for DLC air-conditioning cycle control and low-voltage control if SNOP are connected into distribution systems. Fig. 10 shows the room temperatures in the DLC cycle control between 0 and 60 min at bus 25. It can be seen that the room temperature obtained by the DLC control of [9] increases from 28.2 °C to 29.03 °C, then decrease to about 25.8 °C. The room temperature are better controlled by the proposed control method, and

Table 2
Control status of air-conditioning load.

<table>
<thead>
<tr>
<th>Connected bus</th>
<th>Initial temperature/°C</th>
<th>Ideal control status μ</th>
<th>Practical control status μ</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>26.0</td>
<td>Off</td>
<td>Off</td>
</tr>
<tr>
<td>12</td>
<td>25.1</td>
<td>Off</td>
<td>Off</td>
</tr>
<tr>
<td>14</td>
<td>27.4</td>
<td>Off</td>
<td>Off</td>
</tr>
<tr>
<td>18</td>
<td>28.3</td>
<td>On</td>
<td>On</td>
</tr>
<tr>
<td>25</td>
<td>28.2</td>
<td>On</td>
<td>Off</td>
</tr>
<tr>
<td>45</td>
<td>28.5</td>
<td>On</td>
<td>On</td>
</tr>
<tr>
<td>53</td>
<td>29.4</td>
<td>On</td>
<td>On</td>
</tr>
</tbody>
</table>

Fig. 10. Comparison of room temperatures at bus 25.

Fig. 11. Load-cutting curves of controlled air conditioners.

Fig. 12. Active power losses of the distribution system: (a) Active power loss of network, (b) Active power loss of SNOP.

Fig. 13. Voltage changes of 10 kV Feeders A, B and C caused by SNOP.
the corresponding room temperatures are basically controlled in [26 °C, 28 °C], which never lower than 25.5 °C, or higher than 28.5 °C. This finding implies that the 2nd objective function of minimizing deviation is working, which can maintain the load-cutting is satisfied to the comfort requirements of customer.

4.2. Comparison of load cutting and power loss

Fig. 11 shows the load-cutting curves of air conditioners for this 10 kV distribution system. The total amount of load reduction of controlled air conditioners is closed to the planned load-cutting by electric power dispatching center. The minimum deviation is 0, and the maximum positive deviation is 40 kW and negative deviation is 30 kW respectively. This is because room temperatures of controlled air conditioners are different, which causes practical control pattern may differ from ideal control pattern, which means appearing load-cutting deviation.

For the active power transferred by SNOP, a load-cutting deviation between practical reduction and planned reduction is eliminated by SNOP transmission. For example, the practical load reduction is 40 kW, which is greater than planned reduction in the time-period of 50–55 min. Three SNOP are injected active power from other feeders into this distribution system by 12 kW, 20 kW, 8 kW, which are equal to 40 kW in total referred to load reduction deviation. Fig. 12 shows the curves of active power loss in this distribution system by the DLC control of [9] and the proposed method. The results by the proposed method include the active power losses of the network and the SNOP. The active power loss of the network with DLC and SNOP is obviously smaller than that without SNOP. This finding shows that the SNOP are reducing active power loss, and improving the economic benefits of distribution system operation.

The active power loss of three SNOPs is shown in Fig. 12(b), which has a positive relationship with the transferred power flow of SNOPs. It is known that the load-cutting deviation between practical reduction and planned reduction is eliminated by active power transferred by SNOPs. Therefore, the corresponding total active power losses of three SNOPs are varied with the load-cutting deviation. Compared with Fig. 12(a), these losses are quite smaller than network losses, so that the 3rd objective function is mainly dealing with how to decrease network losses.

The SNOPs need to transfer the maximum active power at 55 min for this 54-bus distribution system in Fig. 11. To analyze the effects of SNOP on the other feeders, Fig. 13 shows the voltage magnitudes of 10 kV feeders A, B and C at 55 min before and after the implementation of the proposed control method. In Fig. 13, the voltage magnitudes are all in the secure ranges of [0.95 p.u., 1.05 p.u.] before and after the proposed reactive power control, and there are slight impacts on the voltage of feeders A, B and C caused by the SNOPs. This is because the transferred active power flow of feeder A, B and C brought by SNOPs is used for eliminating the load-cutting deviation, which is essentially not very large. And the SNOPs can also provide the reactive power compensation for helping voltage magnitudes maintain in a steady range. Thus, the proposed control method has limited effects on the voltage magnitudes of the other feeders.

5. Conclusions

This paper presents an optimal reactive power control method for distribution systems with SNOP and DLC air-conditioning loads. The air-conditioning starting voltage constraints for the connecting point to distribution systems of load aggregators is studied based on the DLC cycle control and the characteristics of starting voltage. This can provide the formula for calculating the critical starting voltage of air-conditioning loads. We take full advantage of SNOP with reactive power compensation characteristics, and eliminate load-cutting deviation between planned load reduction and practical load reduction. This realizes to accurate DLC cycle control for load-cutting, and help electric power dispatch center rapidly shifts and avert power scheduling for peak loads in effective way. We combine demand response technology and voltage control as a comprehensive method to deal with the low-voltage problem at the overload condition of distribution systems. It provides an effective and reasonable approach for demand-side management of smart distribution systems.

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Appendix A. Supplementary data

Supplementary data associated with this article can be found, in the online version, at http://dx.doi.org/10.1016/j.ijepes.2018.06.027.

Reference

[22] Falahi M, Butler-Purry K, Elsani M. Induction motor starting in islanded