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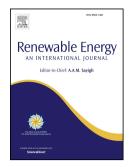
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Identification of Unknown Parameters of a Single Diode Photovoltaic Model Using Particle Swarm Optimization with Binary constraints

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Abstract-Photo-voltaic (PV) is a static medium to convert solar energy directly into 10 11 electricity. In order to predict the performance of a PV system before being installed, a reliable and accurate model design of PV systems is essential. To validate the design of a 12 PV system like maximum power point (MPP) and micro-grid system through simulation, 13 an accurate solar PV model is required. However, information provided by manufacturers 14 15 in data sheets is not sufficient for simulating the characteristic of a PV module under 16 normal as well as under diverse environmental conditions. In this paper, a particle swarm optimization (PSO) technique with binary constraints has been presented to identify the 17 unknown parameters of a single diode model of solar PV module. Multi-crystalline and 18 19 mono-crystalline technologies based PV modules are considered under the present study. Based on the results obtained, it has been found that PSO algorithm yields a high value of 20 accuracy irrespective of temperature variations. 21

Keywords -Photovoltaic (PV) model, maximum power point (MPP), binary constraints,
particle swarm optimization (PSO).

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Nomenclature	2
a_{min}	minimum value of ideality factor
a_{max}	maximum value of ideality factor
b	index of the best individual in population
c_1 and c_2	acceleration factor
D	component of each individual of population
f(.)	objective function to be evaluated
F^{k}_{i}	value of objective function for i th individual of population at iteration k
Gbest ^k	the global best individual of population up to iteration k
$Gbest_{j}^{k}$	j^{th} component of the best individual of population up to iteration k
i	individuals of population $i \in \{1, 2,, N\}$
j	components of an individual $j \in \{1, 2,, D\}$
k	iteration counter ($k \in \{1, 2,, Maxite\}$)
Maxite	maximum number of iterations
Ν	population size
Pbest ^k _i	personal best of i th individual of population up to iteration k
$Pbest^{k}_{i,j}$	personal best j^{th} component of i^{th} individual of population up to iteration k
rand()	uniformly generated random number in the range[0, 1]
R _{s min}	minimum value of series resistance factor
R _{s max}	maximum value of series resistance factor
$R_{p min}$	minimum value of shunt resistance factor
$R_{p max}$	maximum value of shunt resistance factor
Sign(.)	signum function on each variable of the input vector
V	initial velocity of N individuals each having D components
$V^{k}_{i,j}$	velocity of j^{th} component of i^{th} individual of population at iteration k
X	population of N individuals each having D components (variables)
\mathbf{X}_{i}^{k}	i^{th} individual of population X at iteration k, i.e., $X_{i}^{k} = [X_{i,1}^{k}, X_{i,2}^{k}, \dots, X_{i,D}^{k}]$
ω	inertia factor
ω_{max}	maximum value of inertia factor
ω_{min}	minimum value of inertia factor

Abbreviation	S
ABSO	Artificial Bee Swarm optimization
BFA	Bacteria foraging algorithm
CPSO	Chaos particle swarm optimization algorithm
CSA	Cuckoo Search algorithm
EAs	Evolutionary algorithms
GA	Genetic algorithm
MAE	Mean absolute error
MPP	Maximum power point
MPPT	Maximum power point tracking
PSO	Particle swarm optimization
PV	Photo-voltaic
RMSE	Root mean square error
SA	Simulated annealing
STC	Standard test conditions

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35 **1. Introduction**

In the current scenario, socio-economic development and human welfare around the 36 world depends on energy. Fossil fuels account maximum share in the overall generation. 37 However, carbon emissions and depletion are some issues associated with the use of fossil fuels. 38 39 The energy demand around the world is continuously increasing. If this escalating demand is to be met with fossil fuels, the extensive use of fossil fuels will release a large amount of CO₂ and 40 other greenhouse gases. Renewable energy sources on the other hand are abundant in nature and 41 42 contain quite low or no greenhouse-gas emissions. Therefore, it is the necessity of today's world to concentrate on renewable energy sources for electricity generation. Solar energy has been a 43 44 paramount part of renewable energy sources as it is available directly from the sun, whereas wind, wave, hydro etc. are indirectly derived. Solar energy is also available in abundance and is 45 non exhaustible, but the technology to harness solar energy is still improving. Solar PV 46 47 technology exploits the solar radiation and directly converts it into electricity. The utilization of photovoltaic (PV) technology as a source of power at user end is increasing, due to easy 48 49 implementation and low maintenance cost compared to other forms of energy conversion [1]. PV

technology has the highest power density amongst all renewable energy resources with global mean of 170 W/m² [2]. In order to predict the performance of a PV system, a reliable and accurate model design of PV systems is a necessary before being installed.

Performance of the PV system is affected by change in temperature and insolation [3]. Ideally a PV module needs to be operated at maximum power point (MPP). This incorporates advance research in real time optimization techniques like fuzzy logic, artificial neural network, perturb and observe algorithms etc. [4]. Therefore, it is essential to have a comprehensive study and performance analysis of a PV model to predict the outcome of a PV module under diverse atmospheric conditions.

The parameters provided in the manufacturers datasheet under standard test conditions 59 (STC) include short-circuit current, open-circuit voltage, voltage at maximum power, current at 60 maximum power and temperature coefficients of current, voltage and power. Although, provided 61 data is essential but not enough to predict accurate I-V characteristic curves under varying 62 insolation and temperature levels. Single diode PV model is extensively used by several 63 researchers [5-9, 11, 12, 45-47] due to its simplicity. Humada et al. [12] compared and 64 summarizes the techniques for parameter extraction. Further, they have also compared single-65 diode and double diode models for one, two, three, four and five parameters by setting a model 66 evaluation criterion. The study suggests that five parameter (single-diode) model is the most 67 widely model due to its high accuracy and less complex design. 68

The main issue associated with single-diode PV model is to identify five unknown parameters i.e. ideality factor (a), series resistance (R_s), shunt resistance (R_p), reverse saturation current (I_o) and photovoltaic current (I_{pv}). Identification of these parameters by a suitable method is essential in order to accurately predict the PV module characteristics. The methods include analytical approach, iterative approach or real time approach.

- Studies have been carried out using an ideal model of a PV cell which does not include
 series and shunt resistance [13, 14] as shown in Fig. 1.
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- 77

Fig.1. Equivalent circuit of an ideal PV model

5

The previous studies suggested that ideal model is simple but less accurate. Researchers in [10, 15-18] proposed models with four parameters (a, R_s , I_o , I_{pv}) accounting shunt resistance to be infinite. Although, the proposed four parameters model has not been proved accurate yet, it is considered to be favorable as the unknown parameters can be easily identified in comparison to the model with five parameters (a, R_s , R_p , I_o and I_{pv}).

83 To resolve the issue with the necessity of obtaining unknown parameters, a five parameter model based on the values of manufacturer datasheet was presented by Villalva et al. 84 [19]. Value of ideality factor was obtained through trial and error method. The new value of R_s 85 and R_p depends upon the previous value of R_s . The new set of values was determined by 86 continuously increasing R_s and simultaneously computing R_p . These values were determined till 87 MPP of the presented model reaches to the same value as provided in manufacturer's datasheet 88 at STC. Once unknown parameters are extracted, these parameters are fixed and again calculated 89 for same model under the influence of varying insolation and temperature levels. Under standard 90 test conditions (STC), the developed method yields accurate MPP. However accuracy gets 91 compromised under the effect of varying temperature [20]. 92

W. Xiao et al. [21] used a database of MPP acquired from manufacturer in order to produce exact MPP at varying temperatures. At different values of temperature, MPP was matched by regulating ideality factor through iterative technique. The drawback associated herewith is to obtain the availability of MPP for varying temperatures, which is not provided in manufacturer datasheet. Park and Choi [22] employed a parameter extraction method based on datasheet values. MPP error formulation is incorporated as objective function and parameter optimization is achieved by using pattern search algorithm.

Recently numerous evolutionary algorithms (EAs) were adopted to determine unknown parameters of a PV module under consideration. Jena and Ramana [23] presented a critical review based on modeling and parameter identification of a PV cell for simulation. They have analyzed R_s , R_p and two diode model along with different parameter identification schemes (analytical as well as soft computing). In recent years, the metaheuristic optimization algorithms such as genetic algorithm (GA) [24-26], simulated annealing (SA) [27], artificial Bee Swarm optimization (ABSO) algorithm [28, 29], and particle swarm optimization (PSO) [30], have

received considerable attention towards solar cell parameters identification problem.
Metaheuristic algorithms are appropriate selections for resolving the drawback associated with
parameter extraction at varying atmospheric conditions.

In case of GA, serious shortcomings, namely low speed and degradation for highly 110 interactive fitness function has been reported [31, 32]. El-Naggar et al. [27] employed Simulated 111 112 Annealing (SA) to extract the parameters of single and two-diode models for cell and module. The trade-off between the cooling schedule and initial temperature is the major issue that makes 113 SA a less preferable choice. Jieming et al. [33] utilized Cuckoo Search algorithm (CSA) to 114 identify the parameters of the conventional and an advanced form of the single diode model for 115 PV cell and module. Askarzadeh and Rezazadeh [34] employed ABSO to obtain the parameters 116 of the single and double-diode models for PV module. Rajasekar et al. [35] presented a Bacteria 117 Foraging algorithm (BFA) to compute all parameters of the single diode R_P-model under varying 118 operating temperature and insolation values. By utilizing parameters provided on the 119 manufacturer's datasheet, I_{pv} and I_0 were analytically computed, whereas a, R_s , and R_p were 120 obtained by optimizing equation of slope at MPP. 121

Qin and Kimball [36] eliminated the idea of unknown parameters estimation for the SPV 122 model. They exploited the field test data along with PSO algorithm to determine the value of a, 123 R_s and R_p . Measurements of short circuit current and load data were required for the field test. 124 Hengsi and Jonathan [30] employed PSO to extract PV cell parameters from the data measured 125 under real operating conditions of varying insolation and temperature. Wei H et al. [37] used 126 chaos particle swarm optimization algorithm (CPSO) to obtain unknown parameters of the single 127 diode R_p model for a module. In CPSO, the chaotic search mechanism is utilized to re-initiate the 128 stationary particles-causing an enhanced local and global search capability. Ye et al. [38] utilized 129 PSO to determine the cell parameters of the single and two-diode models from the I-V curves. In 130 comparison to GA, PSO was found to be more accurate with better computational speed. On the 131 basis of operating conditions, module technology and type of model researchers have employed 132 numerous parameter extraction techniques having advantages and disadvantages of their own. 133 Among all the techniques, performance of PSO algorithm is found to have an adequate sense of 134 balance between accuracy, speed and complexity. 135

The PSO algorithm is a swarm intelligence optimization algorithm based on observations of the social behavior of bird flocking or fish schooling [28-30, 36-41]. Several authors have utilized and improved many versions of PSO algorithm [28,29,38-41]. However, every version of PSO has different advantage for different complex optimal problem. The major disadvantages observed in PSO are of premature convergence and the loss of diversity in the population.

In order to eliminate the mentioned disadvantage, a novel technique has been presented in this study to compute the unknown parameters (a, R_s and R_p) of a single diode PV model. In the present study, a PSO based single diode model is developed to predict unknown parameters under varying operating conditions. In order to retain these parameters within realistic ranges and considering the effects of temperature variation, a binary constraint has been imposed i.e. by penalizing the objective function when the solution attempts to exceed the predefined parameters boundary limits. The accuracy of the model is assured irrespective of the temperature change.

148 The present study deals with identification of PV model using PSO with binary constraints. An overview of mathematical modeling framework of a PV model is presented and 149 150 further, the problem formulation along with the proposed optimization technique is discussed. Results and performance validation of the proposed technique are discussed in detail. Further, 151 the obtained results are compared with the results of other methods proposed in [16] and [19]. 152 The proposed technique is found to be advantageous as it has the capability of determining 153 154 ideality factor, series and shunt resistance simultaneously without the need of estimating ideality 155 factor and field data measurements. Also, the extracted parameters are computed as a function of insolation and temperature. 156

157

158 2. Mathematical Modeling framework of a PV module based on single diode model.

159 2.1. Ideal PV cell model

160 An ideal PV cell is represented by photo-generated current (I_{pv}) which diverges from the ideal 161 outcome due to electrical and optical losses [23, 41]. Further, the effect of series and parallel 162 resistance are not considered in this simplest PV model. Schematic for an ideal PV model is shown earlier in Figure 1. Terminal current of an ideal model is represented by I-Vcharacteristics and mathematically expressed as:

$$165 I = I_{pv} - I_d (1)$$

The diode current (I_d) signifies diffusion and recombination current in quasi steady state regions of emitter and excess concentration regions of PN junction. This diode current is represented by Shockley equation as:

169
$$I_d = I_0 \{ e^{qV_d/aKT} - 1 \}$$

where *q* is the charge of an electron (1.6x10⁻¹⁹C), *K* is the Boltzmann constant (1.3805x10⁻²³ J/K) *T* is temperature (K), I₀ is leakage current and V_d is the diode voltage.

The ideal mathematical model based on diode equation of Shockley and Queisser isexpressed as:

174
$$I = I_{pv} - I_0 \left(e^{qV_d / aKT} - 1 \right)$$
(3)

175 Ideal solar PV cell does not consider the effect of internal resistance, thus fails to 176 establish an accurate relationship between cell current and voltage.

177 2.2. Practical PV cell Model.

In order to achieve accurate results, a series resistance is introduced to the ideal PV cell model. Although this model is simple but it reveals deficiencies when subjected to temperature variations. To overcome this limitation, the model has been extended further by considering a shunt resistance and is termed as Practical PV cell. Thus, the practical single diode PV or five parameter (I_{pv} , I_0 , a, R_s and R_p) model consists of current producer and a diode with series and shunt resistance as shown in Fig. 2[4-12, 42]. The characteristics I-V curve of a practical PV cell is shown in Fig. 3.

185

186

Fig.2. Equivalent circuit of a practical PV cell

187

(2)

Fig.3. I-V characteristics curve of a PV cell.

The series resistance signifies resistance (ohmic loss) offered to the current flow due to ohmic contact (metal-semiconductor contact) and impurity concentrations along with junction depth. Leakage current across the junction signifies shunt resistance, connected parallel to the diode. The mathematical representation of terminal current in Eq. (1) is modified as:

$$I = I_{Pv} - I_d - V_d / R_p$$

194 $V_d = V + IR_S$

188

195 where *V* is input voltage and I is the terminal current.

196 It is recognized that I-V characteristic curve of a PV cell is affected by both series 197 resistance and shunt resistance. The output voltage is affected by series resistance; while shunt 198 resistance is responsible for reduction in available current [14-15, 43-47].Eq. (3) is modified to 199 obtain the equation of single diode PV model. The terminal current of a single diode(five-200 parameter) model is given by:

201
$$I = I_{pv} - I_0 \left[exp\left(\frac{V + IR_s}{aV_t}\right) - 1 \right] - \frac{V + IR_s}{R_p}$$
(6)

202 where V_T is the thermal voltage (nkT/q).

203 2.3. Modeling of a PV module

A PV module may consist of number of PV cells which can be connected in series or parallel. This series-parallel topology is represented in Fig. 4.

- 206
- 207

Fig.4. Equivalent circuit model of a PV module

The parameters of a PV cell are transformed in order to represent a PV module. Table 1 represents the parameters which are transformed due to series/parallel PV topologies [45, 47].

- 210Table 1: Transformed parameters for series and parallel topologies.
- 211 Terminal current for series-parallel configuration of a PV module can be written as;

(4)

(5)

212
$$I = N_p \left\{ I_{pv} - I_{s1} \left[exp\left(\frac{V + IR_s\left(\frac{N_s}{N_p}\right)}{aN_s V_t}\right) - 1 \right] \right\} - \left\{ \frac{V + IR_s\left(\frac{N_s}{N_p}\right)}{R_{sh}\left(\frac{N_s}{N_p}\right)} \right\}$$
(7)

A single PV module is a particular case of PV cells connected in series. Therefore, the number of cells connected in series (i.e. N_s) will be scaled with V_t . Now, equation (6) can be rewritten as;

216
$$I = I_{pv} - I_0 \left[exp\left(\frac{V + IR_s}{aN_s V_t}\right) - 1 \right] - \frac{V + IR_s}{R_p}$$
(8)

Depending upon the load requirements, the numbers of modules are connected in series to increase voltage levels, whereas modules are connected in parallel to increase current levels.

219 When the terminals of a PV module are short-circuited, the current that flows through the 220 circuit is termed as short-circuit current (I_{sc}). It is the maximum current that flows through a PV 221 cell. I_{sc} of a PV module depends on incident insolation, which is determined by the spectrum of 222 incident light, i.e. AM 1.5 spectrum. I_{sc} also depends on cell area and its ability to absorb incident 223 solar radiation [23].At a given temperature T, V=0 and $I=I_{sc}$, Eq.(8) becomes:

224
$$I_{sc}(T) = \frac{R_p}{R_s + R_p} \left\{ I_{pv} - I_0 \left[exp \left(\frac{I_{sc}(T) + R_s}{aN_s V_t(T)} \right) - 1 \right] \right\}$$
(9)

225 Open circuit voltage (V_{oc}) is the maximum voltage that can be delivered by a PV module. 226 The Open circuit voltage corresponds to forward bias voltage, at which dark current compensates 227 the photo-generated current and V_{oc} is dependent on the density of photo-generated current. At 228 open circuit condition I=0, $V=V_{oc}$ and Eq. (8) becomes;

229
$$V_{oc}(T) = R_p \left\{ I_{pv} - I_0 \left[exp \left(\frac{V_{oc}(T)}{aN_s V_t(T)} \right) - 1 \right] \right\}$$
(10)

At a given temperature, maximum power is determined by the product of maximum current and voltage as shown in Fig. 3. By substituting $I=I_{mp}$ and $V=V_{mp}$, the maximum power at a given temperature can be determined from Eq. (8) as:

233
$$P_{mp}(T) = \frac{R_p V_{mp}(T)}{R_s + R_p} \times \left\{ I_{pv} - I_0 \left[exp \left(\frac{V_{mp}(T) + I_{mp}(T)R_s}{aN_s V_t(T)} \right) - 1 \right] - \frac{V_{mp}(T)}{R_p} \right\}$$
(11)

Equations (9-11) are the data points used by the optimizer to provide the finest set of values for *a*, R_p and R_s . Also, the proportional effect of insolation intensity (G) and operating temperature (T) on the PV output current are given in Eqs. (9-11) [10, 13-15, 42-47].

237 The insolation dependence of PV current is given by;

238
$$I_{pv}(G,T) = \frac{G}{G_{pv}} (I_{pv,n} + K_{I_{sc}} \Delta_T)$$
 (12)

Where $I_{pv,n}$ is PV current and G_n is the solar radiation intensity in W/m² at STC under nominal conditions, K_{Isc} is the temperature coefficient of short circuit current (mA/°C) and $\Delta T (=T-T_n)$ is the difference of temperature between the present moment and STC.

242 2.4. Effect of Temperature

Solar cells work best at low temperature as determined by their material properties. The cell efficiency decreases as the temperature escalates above operating temperature. A substantial part of incident insolation is lost in the form of heat resulting in high temperature of cells. To determine the effect of temperature on maximum power, $P_{mpp,e}(T)$, open circuit voltage, $V_{oc,e}(T)$ and short circuit current, $I_{sc,e}(T)$ at a given temperature are expressed as;

248
$$I_{sc,e}(T) = I_{sc,n} + K_{I_{sc}} \Delta_T$$
 (13)

249
$$V_{oc,e}(T) = V_{oc,n} + K_{V_{oc}} \Delta_T$$
(14)

250
$$P_{mp,e}(T) = P_{mp,n} + K_{P_{mn}}\Delta_T$$
 (15)

where $P_{mpp,n}$, $V_{oc,n}$ and $I_{sc,n}$ respectively represents maximum power, open circuit voltage and short circuit current under nominal circumstances. K_{Voc} and K_{Pmp} are the temperature coefficient of open circuit voltage and maximum power point provided by the manufacturers as shown in Table 2. The datasheets of the considered modules are provided in Ref. [48], [49] and [50].

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256

257

CCEPTED M*a*

259	Table 2: Parameters provided by the manufacturers of different PV modules at STC.
260	The values of maximum voltage and maximum current temperature coefficient are not
261	available and are approximated [57] as:
262	$K_{V_{mp}} \approx K_{V_{oc}}$ (16)
263	$K_{I_{mp}} \approx K_{I_{sc}}$ (17)
264	Therefore, at different temperatures values of V_{mp} and I_{mp} are anticipated as;
265	
266	$V_{mp}(T) = V_{mp,n} + K_{V_{oc}} \Delta_T $ (18)
267	$I_{mp}(T) = I_{mp,n} + K_{I_{sc}} \Delta_T $ (19)
268	3. The Proposed Method and Problem Formulation
269	The PV model, represented in Eq. (8), is a mystical function which includes three
270	unidentified parameters (a, R_s , and R_p). Conventional techniques like Newton–Raphson method

d triggers singularity due to large situation number of the Jacobin matrix. In order to overcome this 271 drawback, a PSO based technique is considered and presented to eradicate the necessity for 272 matrix inversion and partial differentiation. 273

3.1. **Objective** function 274

Based on the manufacture's data given in Table 2, the unidentified parameters of a single 275 diode model as shown in Figure 1 are to be identified in order to match the generated I-V and P-276 277 V curves of the presented model with the manufactures data at a specified temperature. The objective function for calculating PV module unknown parameters like ideality factor (a), series 278 resistance (R_s) and parallel resistance (R_p) is defined as: 279

280
$$minf_{obj} = |f_{Isc}| + |f_{Voc}| + |f_{Pmp}|$$
 (20)

281 Contrasting the distinctive methodology that determines the model parameters by means of MPP only, the objective function in Eq. (20) consists of three data points $[0, I_{sc}]$, $[V_{mp}, I_{mp}]$ and 282 $[V_{oc}, 0]$ for optimization. It also contemplates the consequences of temperature on the PV module 283 for identifying a, R_s and R_p in comparison to other techniques that are dependent on STC only. 284

To normalize the objective function, the numerator and denominator of equations from Eq. (21-23) are obtained from Eqs. (9-11) and (13-15), respectively. This ensures that the range of the terms in the objective function is same.

288
$$fI_{sc}(a, R_s, R_p, T) = \frac{I_{sc}(T)}{I_{sc,e}(T)} - 1$$
 (21)
289
290 $fV_{oc}(a, R_s, R_p, T) = \frac{V_{oc}(T)}{V_{oc,e}(T)} - 1$ (22)
291
292 $fP_{mp}(a, R_s, R_p, T) = \frac{P_{mp}(T)}{P_{mp,e}(T)} - 1$ (23)
293 3.2. Binary Constraints Handling Approach

PV modules' parameters like ideality factor, series resistance and parallel resistance must be within their limits. Three set of constraints are imposed to handle this problem. The constraints are expressed as:

$$297 a_{\min} < a < a_{\max} (24)$$

$$298 \qquad R_{s,\min} < R_s < R_{s,\max} \tag{25}$$

$$299 R_{p,\min} < R_p < R_{p,\max} (26)$$

300 where the minimum and maximum values of the parameters to be determined are represented by 301 the subscripts 'min' and 'max', respectively. The binary constraints considered for simulation are 302 given in Table 3.

303

Table 3: Binary constraints considered for simulation

A binary constraint handling approach is proposed to penalize the objective function if any of the above constraint violates. The proposed approach for handling binary constraints is expressed as follows:

307
$$f_{barrier} = [(sign(a_{min} - a) + sign(a_{max} - a))^2 + (sign(R_{s,min} - R_s) + sign(R_{s,max} - R_s))^2 + (sign(R_{p,min} - R_p) + sign(R_{p,max} - R_p))^2]$$
(27)

where sign(x) is a function return as -1, 0 and 1 if x < 0, x = 0 and x > 0, respectively. This binary constraint handling approach is having advantages over the other constraints handling approach as it only penalizes the objective function if there is a constraint violation. 311 By introducing binary constraint handling approach term into the objective function, i.e., 312 $f_{obj} = |f_{Isc}| + |f_{Voc}| + |f_{Pmp}| + |f_{barrier}|$, the problem is transformed into an unconstrained optimization 313 problem.

The objective function given by Eq. (20) is minimized in order to determine a, R_s and R_p by formulating the PSO approach. In previous studies [37-39, 45-50], PSO algorithm based technique has been used for maximization of the objective function. Whereas in the present study, the objective function is minimized to zero for different values of temperature and insolation using an absolute function.

319 *3.3. PSO algorithm*

Particle swarm optimization is inspired by social and cooperative behavior displayed by 320 various species to fill their needs in the search space. The algorithm is guided by personal 321 experience (Pbest), overall experience (Gbest) and the present movement of the particles to 322 decide their next positions in the search space. Further, the experiences are accelerated by two 323 factors c1 and c2 known as acceleration coefficients, and two random numbers generated between 324 [0, 1], whereas the present movement is multiplied by an inertia factor ' ω ' varying between 325 $[\omega_{min}, \omega_{max}]$. The size of the population is considered as 'N' and the dimension of each element 326 of the population is considered as D, where D represents the total number of variables. The initial 327 solution is denoted as $\mathbf{X} = [\mathbf{X}_1, \mathbf{X}_2, ..., \mathbf{X}_N]^T$, where 'T' denotes the transpose operator. Each 328 individual \mathbf{X}_i (i = 1, 2... N) is given as $\mathbf{X}_i = [X_{i,1}, X_{i,2}, ..., X_{i,D}]$. The initial velocity of the 329 population is denoted as $\mathbf{V} = [\mathbf{V}_1, \mathbf{V}_2, ..., \mathbf{V}_N]^T$. Thus, the velocity of a particle \mathbf{X}_i (i = 1, 2, ..., N) 330 331 is given as $V_i = [V_{i,1}, V_{i,2}, ..., V_{i,D}]$.

332

The flowchart of the proposed PSO-based inverse barrier technique is shown in Fig. 5.

- 333
- 334

Fig.5.Flowchart of the proposed technique

The different steps of PSO are as follows for $\forall I$ and $\forall j$ (where '*i*' represents particle and '*j*' its dimension):

337 Step 1. Set parameter ω_{min} , ω_{max} , c_1 and c_2 of PSO

338	Step 2.	Initialize population of particles having positions \mathbf{X} and velocities \mathbf{V}
339	Step 3.	Set iteration $k = 1$
340	Step 4.	Calculate fitness of particles $F_{i}^{k} = f(\mathbf{X}_{i}^{k})$ and find the index of the best particle b
341	Step 5.	Select <i>Pbest</i> ^k = \mathbf{X}^{k}_{i} and $\mathbf{Gbest}^{k} = \mathbf{X}^{k}_{b}$
342	Step 6.	Take $\omega = \omega_{max} - k \times (\omega_{max} - \omega_{min}) / Max_{iteation}$
343	Step 7.	Update velocity and position of particles as;
344	$V^{k+1}_{i,j} = w$	$\times V_{i,j}^{k} + c_1 \times rand() \times (Pbest_{i,j}^{k} - X_{i,j}^{k}) + c_2 \times rand() \times (Gbest_j^{k} - X_{i,j}^{k}); \forall j and \forall i$
345		$X^{k+1}_{i,j} = X^{k}_{i,j} + V^{k+1}_{i,j}; \forall j \text{ and } \forall i$
346	Step 8.	Evaluate fitness $F^{k+1} = f(\mathbf{X}^{k+1})$ and find the index of the best particle b1
347	Step 9.	Update Pbest of population
348		If $F^{k+1}_{i} < F^{k}_{i}$, then, $Pbest^{k+1}_{i} = X^{k+1}_{i}$ else $Pbest^{k+1}_{i} = Pbest^{k}_{i}$
349	Step 10.	Update Gbest of population
350		If $F^{k+1}{}_{bl} < F^{k}{}_{b}$ then $Gbest^{k+1} = Pbest^{k+1}{}_{bl}$ and set $b = b1$ else $Gbest^{k+1} = Gbest^{k}$
351	Step 11.	If $k < Maxite$ then $k = k + 1$ and go to step 6 else go to step 12
352	Step 12.	Print optimum solution as <i>Gbest^k</i>

Based on the randomly generated population, the PSO technique provides a collection of different solutions for a, R_s and R_p with each new execution of the optimization technique. This provides a set of I-V curves.

The technique provides several I-V and P-V curves as shown in Figure 6 and 7 respectively that meet the objective function to confirm the authentication of the presented algorithm. The circle markers on these curves indicate $[0, I_{sc}]$, $[V_{mp}, I_{mp}]$ and $[V_{oc}, 0]$ which are the points that the I-V curve of the proposed method (indicated by the solid lines) must pass through.

- 361
- 362

363

364

Fig.6. I-V curves obtained by the presented technique

Fig.7 P-V curves obtained by the presented technique.

The overall model error defined for each set of curves in Figure 6 and 7 is represented by the following equation;

367
$$\varepsilon_i = |P_{mp,m_i}(T) - P_{mp,e}(T)| + |V_{mp,m_i}(T) - V_{mp,e}(T)|$$
 (28)

368 Where ε is the overall model error and subscript *i* signifies the specific curve under assessment. 369 From all the possible optimized solution, outcome with the least value of ε is selected as the best 370 solution.

4. Results and Discussions

Performance of the proposed optimization technique (PSO approach) has been investigated first. The parameters such as population size '*ps*' and acceleration coefficients c_1 and c_2 affect the execution of PSO. MATLAB environment is used to conduct this mathematical study. The parameters set up for considered PSO algorithm is shown in Table 4:

376

Table 4: Parameters setup for considered PSO algorithm

377 4.1. Convergence of PSO

In order to study the convergence of PSO for the proposed technique, PV modules of two different technologies have been used. As the temperature varies, for each value of temperature, PSO is implemented and gets terminated after 1000 generations. The optimization has been repeated for 100 times with some new sets of population in order to achieve the average of optimized results. Figure 8 shows the best fitness value versus generations plot for different values of temperature.

384

385

Fig.8. Best fitness versus generations for $T = 0^{\circ}C$ to 75°C for Shell SQ85

The fitness value in curves converges to zero for SQ85 PV module irrelevant of the operating temperature. Similar results can be achieved for KD210GH-2PU and SP70 PV module. It is observed that after every 100 generations the fitness value drops down to zero in 8ms of time to confirm the convergence of the fitness value.

390 4.2. Model validation

Based on the convergence of the proposed algorithm, the PV modules of two different 391 technologies are used to evaluate the proposed model under the present study. The parameters 392 and constraints of these technologies are specified earlier in Tables 2 and 3, respectively. The 393 identified parameters obtained by applying the proposed optimization technique are presented in 394 Figure 9. 395

397

Fig.9. Model parameters for KD210GH-2PU, SP70 and SQ85 at 0°C to 75°C. (a) Ideality factor. (b) Series resistance. (c) Shunt resistance. 398

Ideality factor, series resistance and shunt resistance for two different technologies 399 (Mono-crystalline, KD210GH-2PU and Poly-crystalline, SP70 and SQ85 PV modules) have 400 been extracted by the proposed technique for different values of temperature in the range of T =401 0° C to 75°C. Parameters exhibit non-linear characteristics and the ideality factor is on an urge of 402 403 decrease [Figure 9(a)]. On the other hand, series resistance shows escalating tendency [Figure 9 (b)] for SP70 and SQ85 PV modules. However, KD210GH-2PU PV module indicates the 404 declining tendency in series resistance and inclining trend in ideality factor with increase in 405 406 temperature. In case of shunt resistance, the values identified approximately remains constant for KD210GH-2PU, SP70 and SQ85 PV modules. Series resistance decreases with increase in the 407 ideality factor and vice-versa. However, a slight variation has been observed in case of shunt 408 resistance. 409

Out of 100 independent runs, the best value, mean value and worst value of ideality 410 factor, series resistance and shunt resistance at different temperatures for KD210GH-2PU and 411 SQ85 PV modules are presented in Table 5. 412

413

Table 5: Identified parameters for KD210GH-2PU and SQ85 PV modules

Based on the obtained values of the unknown parameters, I-V and P-V curves of 414 KD210GH-2PU PV module at different insolation and temperature are obtained as shown in 415 Figure 10 and Figure 11 respectively. 416

417

418 **Fig.10.** I–V and P–V curves of proposed model (solid line) and manufacturer's experimental data (circle marker at 419 I_{sc} , P_{mp} and V_{oc}) of KD210GH-2PU (Multi-crystalline) PV module under different irradiation, T = 25°C.

420

421 **Fig.11.** I–V and P–V curves of proposed model (solid line) and manufacturer's experimental data (circle marker at 422 I_{sc} , P_{mp} and V_{oc}) of KD210GH-2PU (Multi-crystalline) PV module at different temperature, G = 1000W/m².

The circle marker at I_{sc} , P_{mp} and V_{oc} indicates manufacturer's experimental data and the results based on the proposed method are indicated by the solid lines. So, the proposed methodology and obtained results clearly indicate that the achieved characteristic curves are quite similar to the manufacturer's data, irrespective of varying atmospheric conditions.

427 *4.3 Comparison of the proposed technique*

In order to keep point of reference of the proposed technique with techniques used in [16] and [19], the relation between absolute error in power and voltage is shown in Figure 12. It is seen that a similar range of accuracy is obtained between the presented method and method used in [19] for different values of temperature. The proposed method offers better accuracy at MPP, whereas, the method presented in [16], shows a considerable amount of error for different values of temperature.

434

435 **Fig.12.** Absolute power error for KD210GH-2PU (Multi-crystalline) at (a) $T = 25 \circ C$, (b) $T = 50 \circ C$, and (c) T = 43675°C, G = 1000W/m2, A.M = 1.5.

437 By making the variations of 1^{0} C in the range of temperature from 0^{0} C to 75^{0} C, the 438 findings based on two other PV modules (SP70 and SQ85) have also been observed. Figure 13 439 illustrates the average result of SP70 PV module for 100 data sets.

440

441 **Fig.13.** Absolute error at MPP for SP-70 (Mono-crystalline) at different temperature,G=1000 W/m², A.M =1.5.

442 Under STC, the error in results illustrated by model [19] is 0.013% for P_{mp} and 0.0515% 443 for V_{mp} at MPP. As the temperature deviates from STC, accuracy decreases up to 2.73% and 444 2.11% at 0°C and 75°C temperature, respectively. Also variation of error in V_{mp} is observed at 445 0°C to 75°C (mean=0.573% and standard deviation=0.289%). In the present study, error of 0.001% for P_{mp} ' and 0.10% for V_{mp} at STC are found. The maximum error 0.011% for P_{mp} is observed for specified temperature range and a standard deviation of 0.045 for V_{mp} is obtained. The obtained value is six times lower as compared to [19]. A similar pattern of results is obtained for SQ85 PV module. Table 6 gives the mean and standard deviation values for SP70 and SQ85 PV modules.

451

Table 6: Comparison of absolute error at MPP (A.M 1.5, 1000 W/m²)

452 It is therefore recommended that in order to attain low modeling error under temperature 453 variation, it is essential to adjust a, R_s and R_p .

454 **5. Conclusions and future works**

A novel approach of optimization technique based on PSO with binary constraints is presented in order to identify the unknown parameters of a single diode model. The proposed method completely eliminates the requirement of assuming the ideality factor. It also includes the temperature variations to identify the unknown parameters.

The evaluation of three different PV modules ensures the robustness of the proposed technique. The two novel approaches have been considered as a point of reference for the proposed technique. Appreciable accuracy in the results is achieved irrespective of temperature variations. The PSO algorithm has been executed 100 times with same initial condition as well as with standard parameter values provided by the manufacturer. The mean of maximum modeling error at MPP is found to be less than 0.02 % for maximum voltage and 0.26 % for maximum power.

466 In future, following works are proposed to improve the performance of PV model:

With growing interests in the study of partial shading and accuracy concerns associated with
 low insolation and large PV installations, performance prediction is important for accurate
 energy yield. More elaborate and accurate models like two-diode model (or three-diode
 model) must be incorporated for performance analysis of the PV system.

Further, one of the promising alternatives for computing the model parameters under these
conditions could be hybrid approach.

Furthermore, the PV models are still based on mono-crystalline and poly-crystalline technology. For instance, amorphous thin film modules have high ideality factor due to low fill factors. However, models presume fill factor in the range of 1 < a < 2. There are very few committed efforts carried out for multi-junction, organic and dye synthesized PV cells. These are emerging areas of interests and particular problems related to them must be resolved.

Finally, problems associated to cell degradations with time and weather conditions must be
 addressed. Additional coefficients can be added to mimic the cell deterioration for different
 module technologies. This effort will offer a greater understanding of the module
 performance over an extensive period of time.

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LIST OF TABLES

S.No.	Parameters of SPV cell	Parameters of PV module (N _s cells connected in series)	Parameters of PV module (N _p cells connected in parallel)
1.	I_{Pv}	I _{Pv}	N _p I _{Pv}
2.	V _t	N _s V _t	Vť
3.	R _s	N _s R _s	R _s /N _p
4.	R _{sh}	N _s R _{sh}	R _{sh} /N _p

Table 1: Transformed parameters for series and parallel topologies.

Table 2: Parameters provided by the manufacturers of different PV modules at STC.

Parameters	Unit	Multi-crystalline	Mono-crystalline	Mono-crystalline	
1 urumeters	Chit	Kyocera KD210GH-2PU	Shell SP70	Shell SQ85	
I _{sc}	А	A 8.58 4.70		5.45	
V _{oc}	V	33.20	21.40	22.20	
I _{mp}	А	7.90	4.25	4.95	
V _{mp}	V	26.60	16.50	17.20	
K _{Voc}	$(mV/^{o}C)$	-120	-76	-72.50	
K _{Isc}	$(mA/^{o}C)$	5.15	2	0.8	
K _{Pmp}	(%/°C)	-0.45	-0.45	-0.43	
N _s	Nos.	54	36	36	

Table 3: Binary constraints considered for simulation

Parameters	Unit	Multi-crystalline	Mono-crystalline	Mono-crystalline	
	Unit	Kyocera, KD210GH-2PU	Shell, SP70	Shell, SQ85	
a_{min}		0.5	0.5	0.5	
a _{max}	-)	2.0	2.0	2.0	
R _{Pmin}	ohm	0.001	0.001	0.001	
R _{Pmax}	ohm	1.0	1.0	1.0	
R _{Smin}	ohm	50	50	50	
R _{Smax}	ohm	200	200	200	

S.No.	Parameters	Values
1.	Population size (ps)	60
2.	Acceleration coefficients ($c_1=c_2$)	2.0
3.	Minimum value of inertia factor, (ω_{min})	0.4
4.	Maximum value of inertia factor, (ω_{max})	0.9
5.	Maximum iteration	1000
6.	Maximum tolerance for objective function	10-8

Table 4: Parameters setup for considered PSO algorithm

Table 5: Identified parameters for KD210GH-2PU and SQ85 PV modules

Temperature	Values	KYOCE	RA-KD2	10GH-2PU	SHELL-SQ85		
Temperature	v urdes	а	$R_{s}(\Omega)$	$R_{p}\left(\Omega ight)$	a	Rs (Ω)	Rp (Ω)
	Best Value (G _{best})	1.6016	0.0012	104.5979	1.6056	0.0284	55.7392
$25^{0}C$	Mean Value (G _{mean})	1.4809	0.0909	142.7663	1.5603	0.2161	130.1744
	Worst Value (G _{worst})	0.6785	0.4989	193.9616	0.9177	0.5473	193.6260
	Best Value (G _{best})	1.5996	0.0010	199.9060	1.5998	0.0010	199.9962
50 ⁰ C	Mean Value (G _{mean})	1.5582	0.0186	165.0791	1.5448	0.0309	181.9622
	Worst Value (G _{worst})	0.5577	0.4393	107.2338	0.6785	0.4989	193.9616
75 ⁰ C	Best Value (G _{best})	1.5996	0.0010	199.9773	1.5998	0.0009	199.9274
	Mean Value (G _{mean})	1.5793	0.0099	158.1982	1.5726	0.0160	171.7543
	Worst Value (G _{worst})	0.5517	0.4393	107.2338	0.6786	0.4988	193.9616

Table 6: Comparison of absolute error at MPP (A.M 1.5, 1000 W/m²)

		S	Shell SP70		Shell SQ85			
	Mean	(%)	Standard Dev	Standard Deviation (%)			Standard Deviation (%)	
Method	P _{mp} Error	V _{mp} Error	P _{mp} Error	V _{mp} Error	P _{mp} Error	V _{mp} Error	P _{mp} Error	V _{mp} Error
[19]	1.246	0.573	0.726	0.289	1.373	0.420	0.829	0.282
Proposed	0.003	0.068	0.002	0.045	0.001	0.077	0.002	0.047

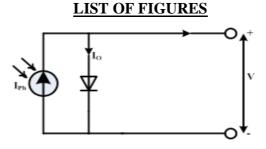


Fig.1. Equivalent circuit of an ideal PV model

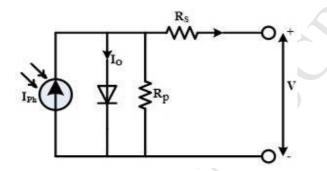


Fig.2. Equivalent circuit of a practical PV cell

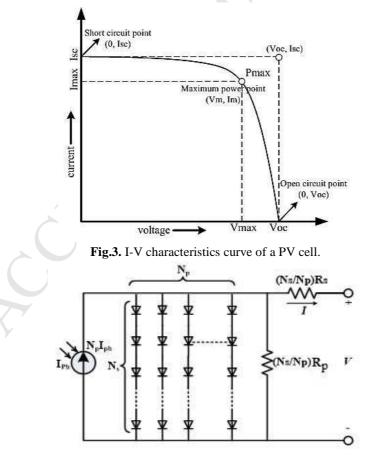


Fig.4. Equivalent circuit model of a PV module

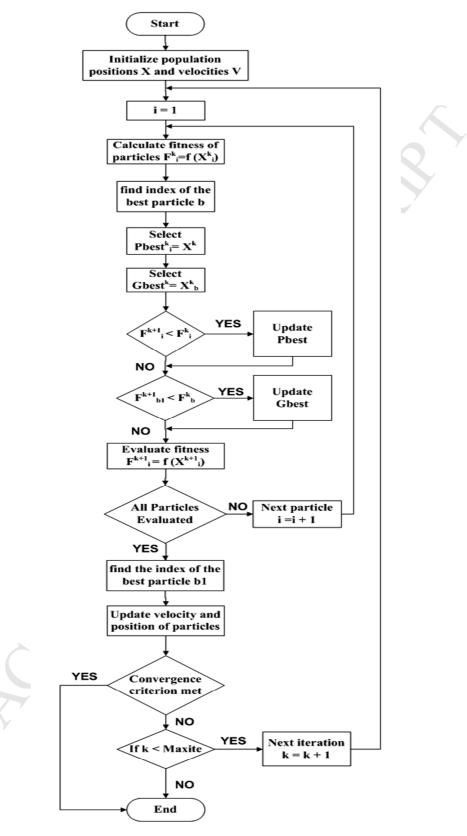


Fig.5. Flowchart of the proposed technique

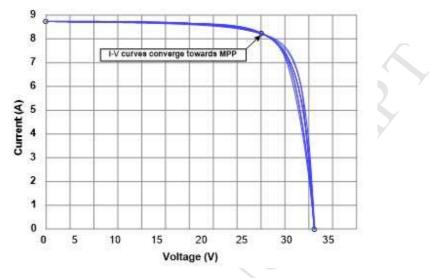


Fig.6. I-V curves obtained by the presented technique

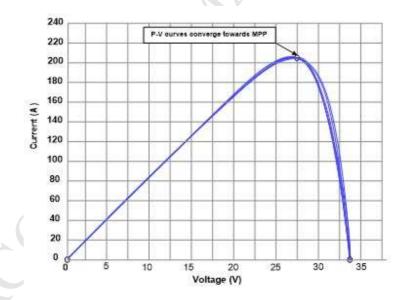


Fig.7 P-V curves obtained by the presented technique.

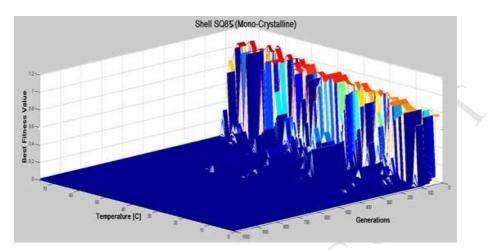


Fig.8. Best fitness versus generations for $T = 0^{\circ}C$ to $75^{\circ}C$ for Shell SQ85

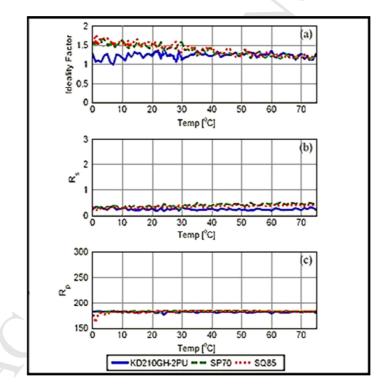


Fig.9. Model parameters for KD210GH-2PU, SP70 and SQ85 at 0°C to 75°C. (a) Ideality factor. (b) Series resistance. (c) Shunt resistance.

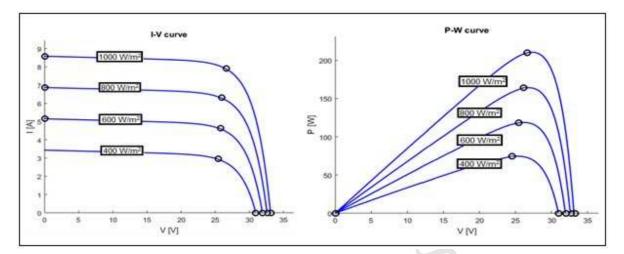


Fig.10. I–V and P–V curves of proposed model (solid line) and manufacturer's experimental data (circle marker at I_{sc} , P_{mp} and V_{oc}) of KD210GH-2PU (Multi-crystalline) PV module under different irradiation, T = 25°C.

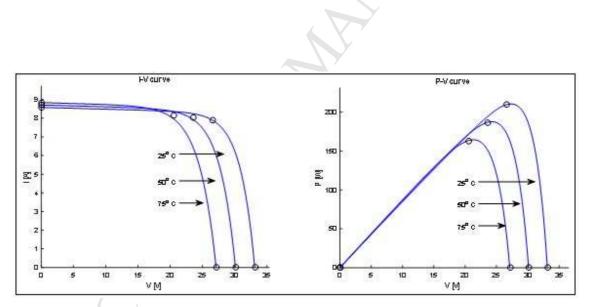


Fig.11. I–V and P–V curves of proposed model (solid line) and manufacturer's experimental data (circle marker at I_{sc} , P_{mp} and V_{oc}) of KD210GH-2PU (Multi-crystalline) PV module at different temperature, G = 1000W/m².

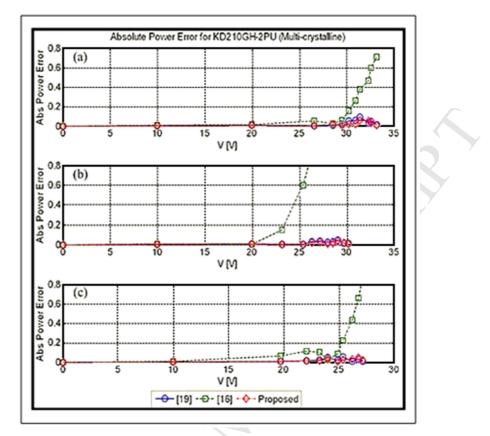


Fig.12. Absolute power error for KD210GH-2PU (Multi-crystalline) at (a) T = 25°C, (b) T = 50°C, and (c) T = 75°C, G = 1000W/m2, A.M = 1.5.

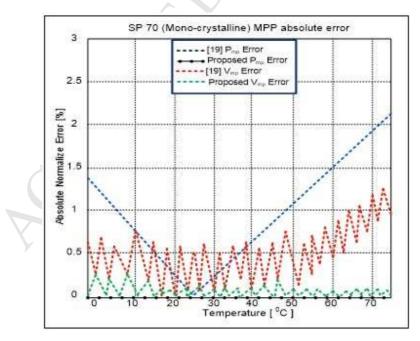


Fig.13. Absolute error at MPP for SP-70 (Mono-crystalline) at different temperature, G=1000 W/m², A.M =1.5.

HIGHLIGHTS

- In the proposed study, unknown parameters (ideality factor, series resistance, shunt resistance) of the single diode model are identified considering binary constraints using PSO based approach.
- Based on the results of the proposed technique the characteristic curve of the PV module is validated with the manufacturer's experimental data.
- The two novel approaches have been considered as a point of reference for the proposed technique.

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